(Dynamic Games)

(Dynamic Games)

Outline

(Dynamic Games)

Outline

(September 3, 2007)

• Game tree, information and memory

(Dynamic Games)

Outline

- Game tree, information and memory
- Strategies and reduced games

(Dynamic Games)

Outline

- Game tree, information and memory
- Strategies and reduced games
- Subgame perfect equilibrium

(Dynamic Games)

Outline

- Game tree, information and memory
- Strategies and reduced games
- Subgame perfect equilibrium
- Repeated Games (of complete information with perfect monitoring)

(Dynamic Games)

Outline

- Game tree, information and memory
- Strategies and reduced games
- Subgame perfect equilibrium
- Repeated Games (of complete information with perfect monitoring)
- Negotiation: Strategic approach

- Chess, poker, ...
- Examples: Stackelberg duopoly (leader / follower)
 - Entry deterrence, reputation

- Chess, poker, ...
- Examples: Stackelberg duopoly (leader / follower)
 - Entry deterrence, reputation

Refining the Nash equilibrium concept. For example, excluding incredible threats (subgame perfect Nash equilibrium, Selten, 1965)

- Chess, poker, ...
- Examples: Stackelberg duopoly (leader / follower)
 - Entry deterrence, reputation

Refining the Nash equilibrium concept. For example, excluding incredible threats (subgame perfect Nash equilibrium, Selten, 1965)

Example : Threat of price war from a monopoly (incumbent) in case of entry

- Chess, poker, ...
- Examples: Stackelberg duopoly (leader / follower)
 - Entry deterrence, reputation

Refining the Nash equilibrium concept. For example, excluding incredible threats (subgame perfect Nash equilibrium, Selten, 1965)

Example : Threat of price war from a monopoly (incumbent) in case of entry

But we will see that every extensive form game can be written in normal form, by appropriately defining players' strategies

> Set of players
$$N = \{1, 2, \dots, i, \dots, n\}$$

> Set of players
$$N = \{1, 2, \dots, i, \dots, n\}$$

\succ Set of nodes X

- > Set of players $N = \{1, 2, \dots, i, \dots, n\}$
- > Set of nodes X
 - Transitive and asymmetric partial order

- > Set of players $N = \{1, 2, \dots, i, \dots, n\}$
- \succ Set of nodes X
 - Transitive and asymmetric partial order

 $x \prec x'$ if and only if x precedes x'

• One initial node: without predecessors and predecessor of all the other nodes

- > Set of players $N = \{1, 2, \dots, i, \dots, n\}$
- > Set of nodes X
 - Transitive and asymmetric partial order

- One initial node: without predecessors and predecessor of all the other nodes
- Every other node has one and only one predecessor

- > Set of players $N = \{1, 2, \dots, i, \dots, n\}$
- \succ Set of nodes X
 - Transitive and asymmetric partial order

- One initial node: without predecessors and predecessor of all the other nodes
- Every other node has one and only one predecessor
- Terminal nodes: without successors

- > Set of players $N = \{1, 2, \dots, i, \dots, n\}$
- > Set of nodes X
 - Transitive and asymmetric partial order

- One initial node: without predecessors and predecessor of all the other nodes
- Every other node has one and only one predecessor
- Terminal nodes: without successors
- Decision node: non-terminal node associated to a player or to Nature (chance)

- > Set of players $N = \{1, 2, \dots, i, \dots, n\}$
- > Set of nodes X
 - Transitive and asymmetric partial order

- One initial node: without predecessors and predecessor of all the other nodes
- Every other node has one and only one predecessor
- Terminal nodes: without successors
- Decision node: non-terminal node associated to a player or to Nature (chance)
- Set of players' actions at decision nodes (vertexes of the tree)

- > Set of players $N = \{1, 2, \dots, i, \dots, n\}$
- > Set of nodes X
 - Transitive and asymmetric partial order

- One initial node: without predecessors and predecessor of all the other nodes
- Every other node has one and only one predecessor
- Terminal nodes: without successors
- Decision node: non-terminal node associated to a player or to Nature (chance)
- Set of players' actions at decision nodes (vertexes of the tree)
- > $(H_i)_{i \in N}$: partitions of decision nodes into information sets. $\forall x' \in h_i(x)$, the set of actions available to player i at x' is the same as at x

- > Set of players $N = \{1, 2, \dots, i, \dots, n\}$
- \succ Set of nodes X
 - Transitive and asymmetric partial order

- One initial node: without predecessors and predecessor of all the other nodes
- Every other node has one and only one predecessor
- Terminal nodes: without successors
- Decision node: non-terminal node associated to a player or to Nature (chance)
- Set of players' actions at decision nodes (vertexes of the tree)
- > $(H_i)_{i \in N}$: partitions of decision nodes into information sets. $\forall x' \in h_i(x)$, the set of actions available to player i at x' is the same as at x
- > $(u_i)_{i \in N}$: players' payoffs at terminal nodes

- > Set of players $N = \{1, 2, \dots, i, \dots, n\}$
- > Set of nodes X
 - Transitive and asymmetric partial order

- One initial node: without predecessors and predecessor of all the other nodes
- Every other node has one and only one predecessor
- Terminal nodes: without successors
- Decision node: non-terminal node associated to a player or to Nature (chance)
- Set of players' actions at decision nodes (vertexes of the tree)
- ➤ $(H_i)_{i \in N}$: partitions of decision nodes into information sets. $\forall x' \in h_i(x)$, the set of actions available to player i at x' is the same as at x
- > $(u_i)_{i \in N}$: players' payoffs at terminal nodes
- Probabilities of Nature's moves



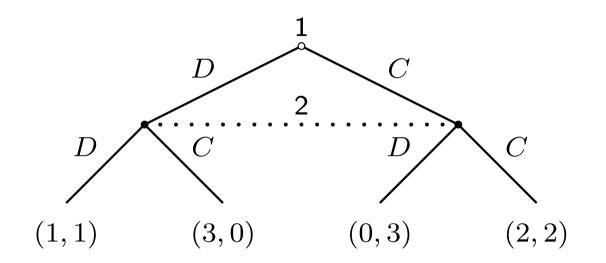




Prisoner Dilemma

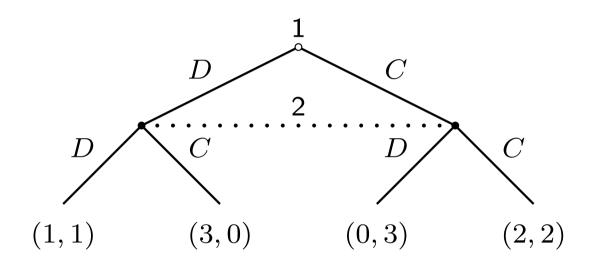


Prisoner Dilemma





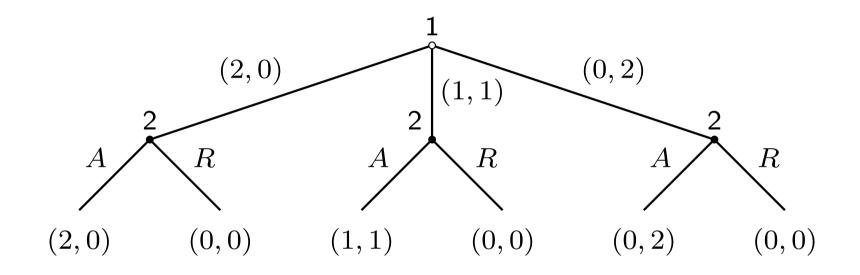
Prisoner Dilemma



 \Rightarrow Two repetitions with perfect monitoring ...

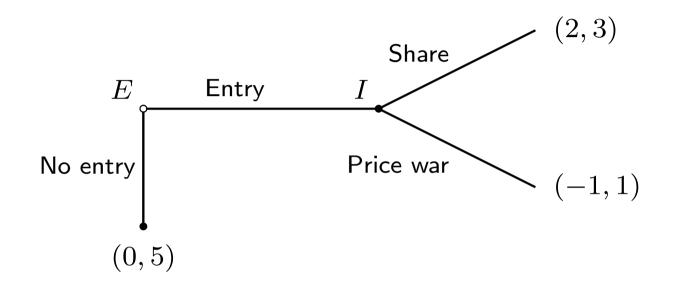
Ultimatum Game (finite)

Ultimatum Game (finite)

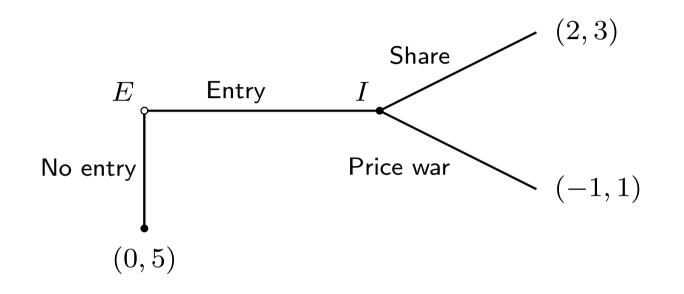


Entry Game

Entry Game



Entry Game



Another example: owing a gun pdf
 (Compare the simultaneous and the sequential game)

If every information set is a singleton then

If every information set is a singleton then

• every player knows all past events

If every information set is a singleton then

- every player knows all past events
- every player observes past players' actions (perfect monitoring)

If every information set is a singleton then

- every player knows all past events
- every player observes past players' actions (perfect monitoring)
- there is no simultaneous moves

If every information set is a singleton then

- every player knows all past events
- every player observes past players' actions (perfect monitoring)
- there is no simultaneous moves

Game of **perfect information** (chess, tic-tac-toe, Stackelberg duopoly, ultimatum game, entry game)

If every information set is a singleton then

- every player knows all past events
- every player observes past players' actions (perfect monitoring)
- there is no simultaneous moves

Game of **perfect information** (chess, tic-tac-toe, Stackelberg duopoly, ultimatum game, entry game)

Otherwise, the game is of **imperfect information** (poker, Bertrand/Cournot duopoly, prisoner dilemma)

If some players don't know the rules of the game, e.g.,

If some players don't know the rules of the game, e.g.,

– players' preferences

If some players don't know the rules of the game, e.g.,

players' preferences
 available actions

If some players don't know the rules of the game, e.g.,

- players' preferences
 available actions
- identity or number of players

If some players don't know the rules of the game, e.g.,

- players' preferences
 available actions
- identity or number of players
 ordering of decisions

If some players don't know the rules of the game, e.g.,

- players' preferences
 available actions
- identity or number of players
 ordering of decisions

the game is of **incomplete information**

If some players don't know the rules of the game, e.g.,

- players' preferences
 available actions
- identity or number of players
 ordering of decisions

the game is of incomplete information

Harsanyi (1967–1968) proposes a transformation

Incomplete information **m** imperfect information

If some players don't know the rules of the game, e.g.,

- players' preferences
 available actions
- identity or number of players
 ordering of decisions

the game is of incomplete information

Harsanyi (1967–1968) proposes a transformation

Incomplete information **m** imperfect information

by introducing a fictitious player, called Nature, who determines random events of the game (the states of Nature, including players' beliefs), with a common probability distribution

Particular case: Bayesian games

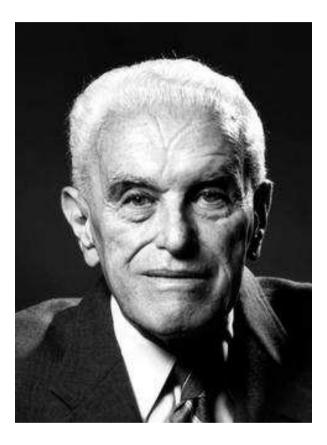


Figure 1: John C. Harsanyi (1920–2000)



A seller of a good chooses a unit price p. Afterwards, a buyer chooses a quantity q

A seller of a good chooses a unit price p. Afterwards, a buyer chooses a quantity q

 \Rightarrow Incomplete information because players do not necessarily know the seller's profit function and the buyer's utility function (e.g., unknown quality of the product)

A seller of a good chooses a unit price p. Afterwards, a buyer chooses a quantity q

 \Rightarrow Incomplete information because players do not necessarily know the seller's profit function and the buyer's utility function (e.g., unknown quality of the product)

 \Rightarrow Set of states of Nature Ω , with a common prior probability $\mu \in \Delta(\Omega)$

A seller of a good chooses a unit price p. Afterwards, a buyer chooses a quantity q

 \Rightarrow Incomplete information because players do not necessarily know the seller's profit function and the buyer's utility function (e.g., unknown quality of the product)

 \Rightarrow Set of states of Nature Ω , with a common prior probability $\mu \in \Delta(\Omega)$

Simplest setting:

A seller of a good chooses a unit price p. Afterwards, a buyer chooses a quantity q

 \Rightarrow Incomplete information because players do not necessarily know the seller's profit function and the buyer's utility function (e.g., unknown quality of the product)

 \Rightarrow Set of states of Nature Ω , with a common prior probability $\mu \in \Delta(\Omega)$

Simplest setting:

• a state of Nature for each level of quality: $\Omega = \{\omega_1, \omega_2\}$

A seller of a good chooses a unit price p. Afterwards, a buyer chooses a quantity q

 \Rightarrow Incomplete information because players do not necessarily know the seller's profit function and the buyer's utility function (e.g., unknown quality of the product)

 \Rightarrow Set of states of Nature Ω , with a common prior probability $\mu \in \Delta(\Omega)$

Simplest setting:

- a state of Nature for each level of quality: $\Omega = \{\omega_1, \omega_2\}$
- the seller always knows the quality

A seller of a good chooses a unit price p. Afterwards, a buyer chooses a quantity q

 \Rightarrow Incomplete information because players do not necessarily know the seller's profit function and the buyer's utility function (e.g., unknown quality of the product)

 \Rightarrow Set of states of Nature Ω , with a common prior probability $\mu \in \Delta(\Omega)$ Simplest setting:

- a state of Nature for each level of quality: $\Omega = \{\omega_1, \omega_2\}$
- the seller always knows the quality
- the buyer never knows the quality

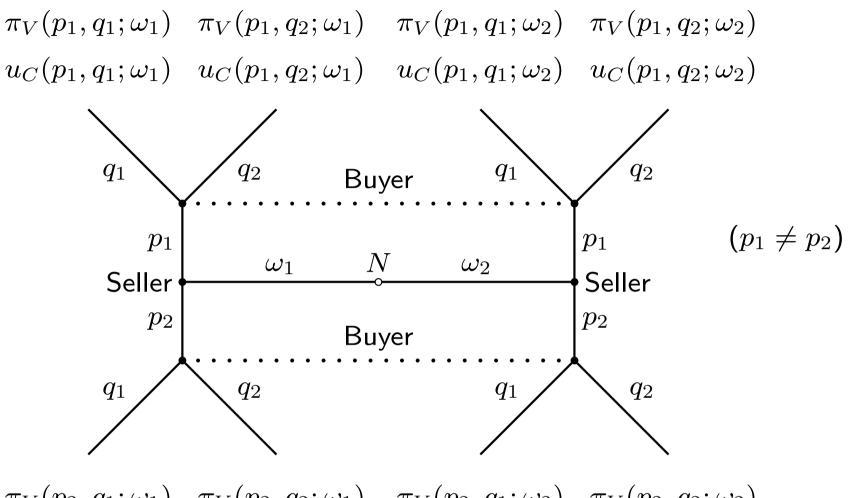
A seller of a good chooses a unit price p. Afterwards, a buyer chooses a quantity q

 \Rightarrow Incomplete information because players do not necessarily know the seller's profit function and the buyer's utility function (e.g., unknown quality of the product)

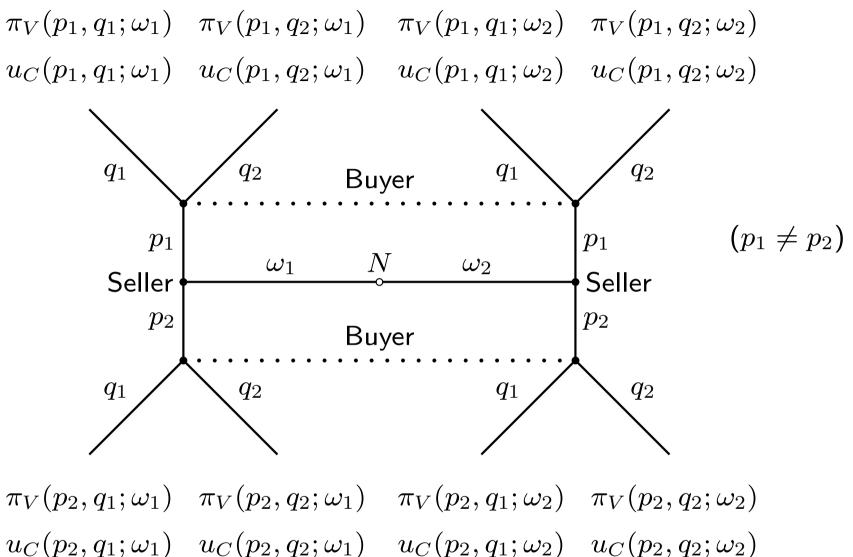
⇒ Set of states of Nature Ω , with a common prior probability $\mu \in \Delta(\Omega)$ Simplest setting:

- a state of Nature for each level of quality: $\Omega = \{\omega_1, \omega_2\}$
- the seller always knows the quality
- the buyer never knows the quality

Player 1 (the informed player) is called the **sender** and player 2 (the uninformed player) is the **receiver**



 $egin{aligned} \pi_V(p_2,q_1;\omega_1) & \pi_V(p_2,q_2;\omega_1) & \pi_V(p_2,q_1;\omega_2) & \pi_V(p_2,q_2;\omega_2) \ u_C(p_2,q_1;\omega_1) & u_C(p_2,q_2;\omega_1) & u_C(p_2,q_1;\omega_2) & u_C(p_2,q_2;\omega_2) \end{aligned}$



When players' payoff do not depend on the sender's action, the signaling game is called a **cheap talk game**

Perfect / Imperfect Memory

Perfect / Imperfect Memory

A game is of **perfect memory** if each player remembers his previous actions and information

Perfect / Imperfect Memory

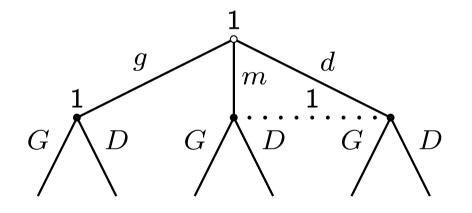
A game is of **perfect memory** if each player remembers his previous actions and information

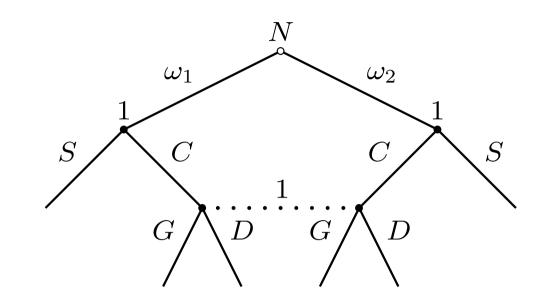
Examples of games with imperfect memory:

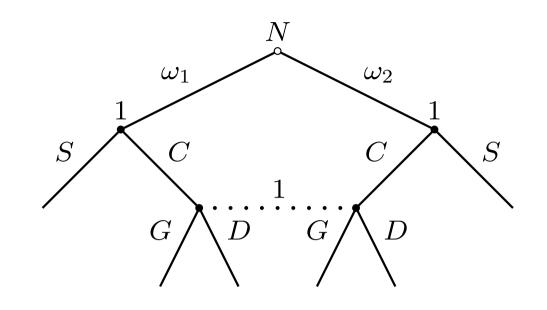
Perfect / Imperfect Memory

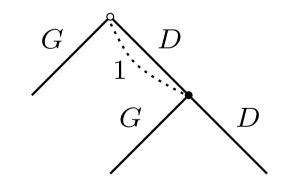
A game is of **perfect memory** if each player remembers his previous actions and information

Examples of games with **im**perfect memory:









A pure strategy is a plan of action at every information set of the player (reached or not). Hence, given the real states of Nature and a strategy profile, the path followed in the game tree is perfectly defined from every possible node

A pure strategy is a plan of action at every information set of the player (reached or not). Hence, given the real states of Nature and a strategy profile, the path followed in the game tree is perfectly defined from every possible node

More precisely, a pure strategy of player i is a function

A pure strategy is a plan of action at every information set of the player (reached or not). Hence, given the real states of Nature and a strategy profile, the path followed in the game tree is perfectly defined from every possible node

More precisely, a pure strategy of player i is a function

 $s_i: H_i \to A_i$ $h_i \mapsto a_i \in A(h_i)$

which associates to every information set $h_i \in H_i$ an action $a_i \in A(h_i)$, where $A(h_i)$ is the set of actions available at h_i

Strategy profile + probability distribution over Ω

Strategy profile + probability distribution over Ω

Probability distribution over terminal nodes

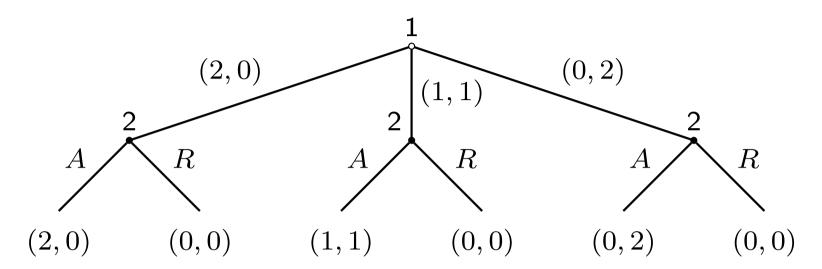
Strategy profile + probability distribution over Ω

Probability distribution over terminal nodes

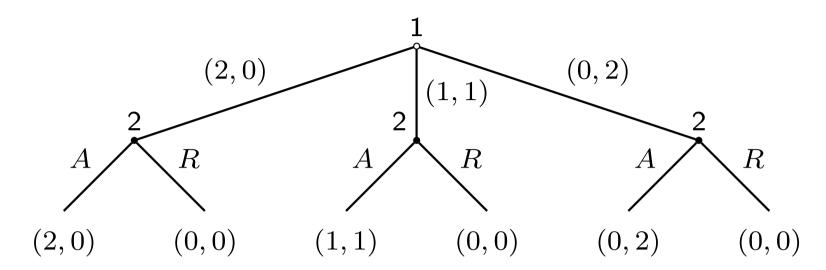
Expected utilities for every strategy profile Normal form game

Example: Ultimatum Game (finite)

Example: Ultimatum Game (finite)



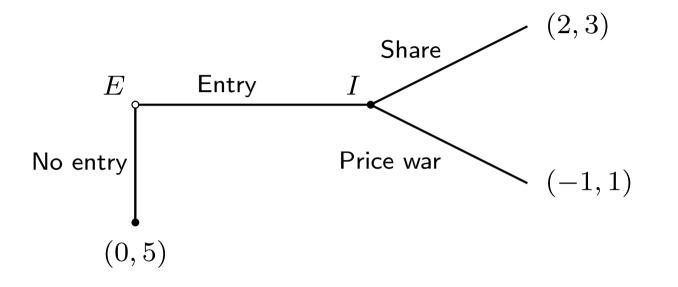
Example: Ultimatum Game (finite)



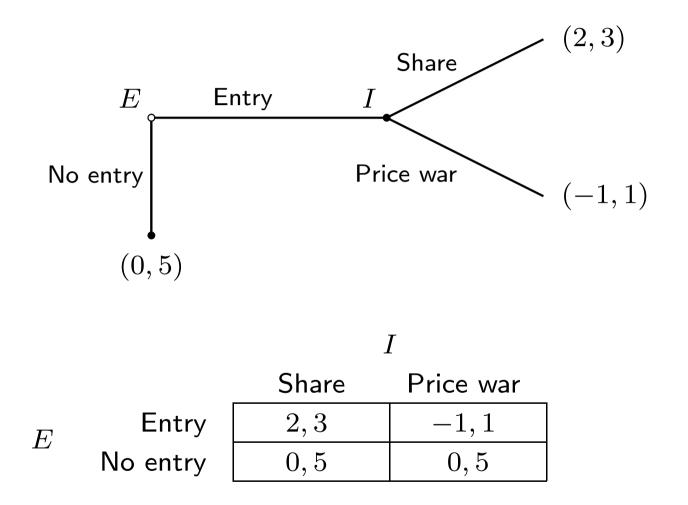
	AAA	RAA	ARA	AAR	RRA	RAR	ARR	RRR
(2, 0)	(2, 0)	(0, 0)	(2, 0)	(2, 0)	(0, 0)	(0,0)	(2, 0)	(0, 0)
(1,1)	(1, 1)	(1, 1)	(0, 0)	(1, 1)	(0, 0)	(1,1)	(0, 0)	(0, 0)
(0,2)	(0, 2)	(0, 2)	(0,2)	(0, 0)	(0, 2)	(0, 0)	(0, 0)	(0, 0)

Example: Entry Game

Example: Entry Game



Example: Entry Game







$$\sigma_i \in \Sigma_i \equiv \Delta(S_i)$$



$$\sigma_i \in \Sigma_i \equiv \Delta(S_i)$$

 \Rightarrow In extensive form games we can define



 $\sigma_i \in \Sigma_i \equiv \Delta(S_i)$

 \Rightarrow In extensive form games we can define

✓ Nash equilibrium (in pure and mixed strategies)



 $\sigma_i \in \Sigma_i \equiv \Delta(S_i)$

- \Rightarrow In extensive form games we can define
 - ✓ Nash equilibrium (in pure and mixed strategies)
 - ✓ dominated strategies (and iterated elimination)



 $\sigma_i \in \Sigma_i \equiv \Delta(S_i)$

- \Rightarrow In extensive form games we can define
 - ✓ Nash equilibrium (in pure and mixed strategies)
 - ✓ dominated strategies (and iterated elimination)
 - $\checkmark\,$ the value if the game is 0-sum

as in normal form games





A local strategy β_{h_i} of player *i* at information set h_i is a probability distribution over the set of actions at h_i : $\beta_{h_i} \in \Delta(A(h_i))$

A local strategy β_{h_i} of player *i* at information set h_i is a probability distribution over the set of actions at h_i : $\beta_{h_i} \in \Delta(A(h_i))$

A behavior strategy β_i of player *i* is a vector of local strategies $\beta_i = (\beta_{h_i})_{h_i \in H_i}$

A local strategy β_{h_i} of player *i* at information set h_i is a probability distribution over the set of actions at h_i : $\beta_{h_i} \in \Delta(A(h_i))$

A behavior strategy β_i of player *i* is a vector of local strategies $\beta_i = (\beta_{h_i})_{h_i \in H_i}$

Example: Ultimatum Game

A local strategy β_{h_i} of player *i* at information set h_i is a probability distribution over the set of actions at h_i : $\beta_{h_i} \in \Delta(A(h_i))$

A behavior strategy β_i of player *i* is a vector of local strategies $\beta_i = (\beta_{h_i})_{h_i \in H_i}$

Example: Ultimatum Game

• Mixed strategy of player $1 \Leftrightarrow$ behavior strategy of player 1

A local strategy β_{h_i} of player *i* at information set h_i is a probability distribution over the set of actions at h_i : $\beta_{h_i} \in \Delta(A(h_i))$

A behavior strategy β_i of player *i* is a vector of local strategies $\beta_i = (\beta_{h_i})_{h_i \in H_i}$

Example: Ultimatum Game

- Mixed strategy of player $1 \Leftrightarrow$ behavior strategy of player 1
- Mixed strategy of player 2 : probability distribution over $\{AAA, \ldots, RRR\}$

A local strategy β_{h_i} of player *i* at information set h_i is a probability distribution over the set of actions at h_i : $\beta_{h_i} \in \Delta(A(h_i))$

A behavior strategy β_i of player *i* is a vector of local strategies $\beta_i = (\beta_{h_i})_{h_i \in H_i}$

Example: Ultimatum Game

- Mixed strategy of player $1 \Leftrightarrow$ behavior strategy of player 1
- Mixed strategy of player 2 : probability distribution over $\{AAA, \ldots, RRR\}$
- Behavior strategy of player 2 : 3 probability distributions over $\{A, R\}$

A local strategy β_{h_i} of player *i* at information set h_i is a probability distribution over the set of actions at h_i : $\beta_{h_i} \in \Delta(A(h_i))$

A behavior strategy β_i of player *i* is a vector of local strategies $\beta_i = (\beta_{h_i})_{h_i \in H_i}$

Example: Ultimatum Game

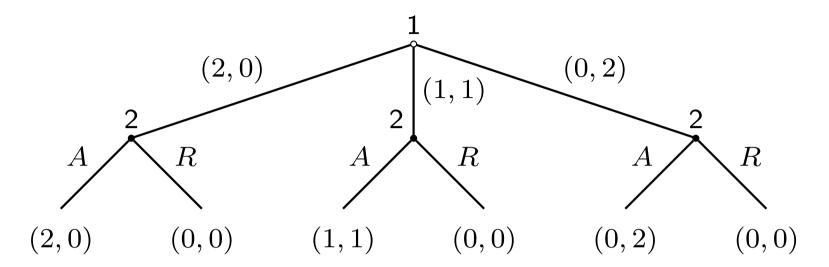
- Mixed strategy of player $1 \Leftrightarrow$ behavior strategy of player 1
- Mixed strategy of player 2 : probability distribution over $\{AAA, \ldots, RRR\}$
- Behavior strategy of player 2 : 3 probability distributions over $\{A, R\}$

A mixed strategy is outcome equivalent to a behavior strategy if whatever others' strategies, the two strategies generate the same probability distribution over terminal nodes

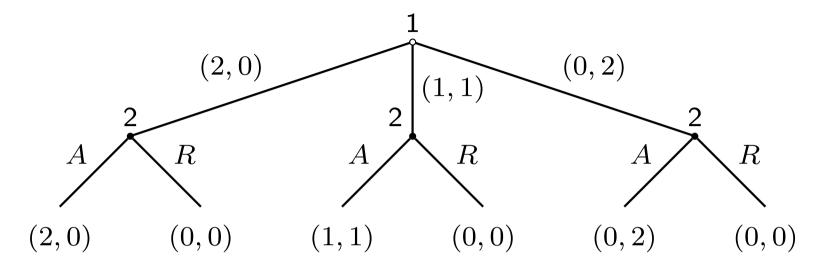
Extensive Form Games

Example.

Example. In the ultimatum game

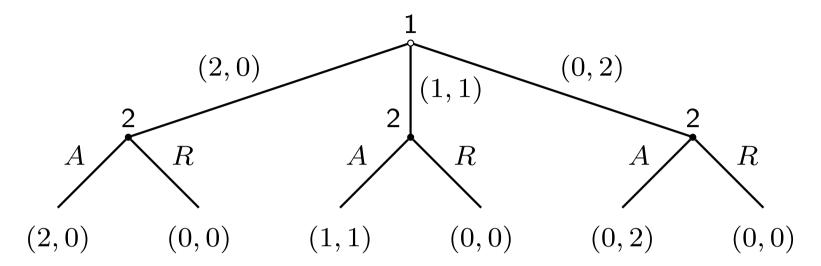


Example. In the ultimatum game



the mixed strategy $\sigma_2(AAA) = \sigma_2(ARA) = \sigma_2(AAR) = 1/3$ is equivalent to the behavior strategy $\beta_{h_2}(A) = 1$, $\beta_{h'_2}(A) = \beta_{h''_2}(A) = 2/3$, where h_2 , h'_2 , h''_2 are the information sets of player 2

Example. In the ultimatum game

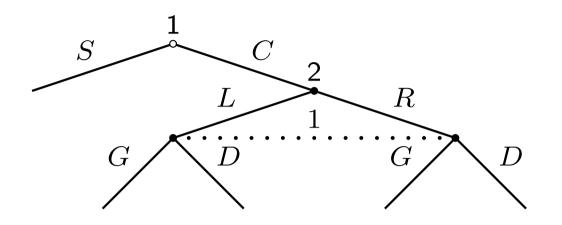


the mixed strategy $\sigma_2(AAA) = \sigma_2(ARA) = \sigma_2(AAR) = 1/3$ is equivalent to the behavior strategy $\beta_{h_2}(A) = 1$, $\beta_{h'_2}(A) = \beta_{h''_2}(A) = 2/3$, where h_2 , h'_2 , h''_2 are the information sets of player 2

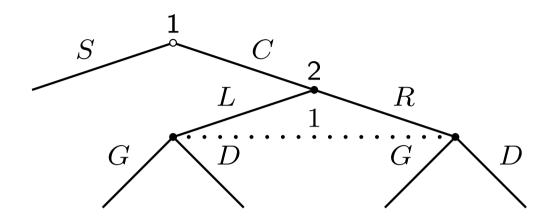
Remark: Several mixed strategies are equivalent to β_2 (for example, $\sigma_2(AAA) = 2/3$ and $\sigma_2(ARR) = 1/3$)

Example.

Example.



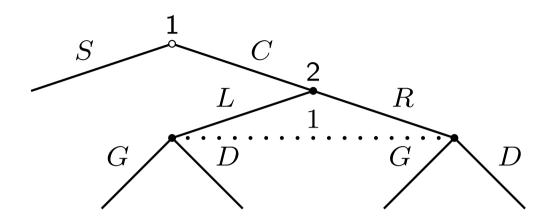
Example.



The mixed strategy

$$\sigma_1(S,D) = 0.4, \ \sigma_1(S,G) = 0.1, \ \sigma_1(C,D) = 0.5$$

Example.



The mixed strategy

$$\sigma_1(S,D) = 0.4, \ \sigma_1(S,G) = 0.1, \ \sigma_1(C,D) = 0.5$$

is equivalent to the behavior strategy of player 1 that consists in playing S and C with probability 1/2, and D with probability 1

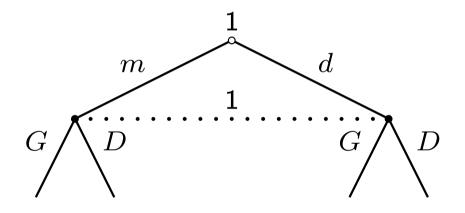
In every finite extensive form game with perfect memory, for every mixed strategy (behavior strategy, resp.) there exists an outcome equivalent behavior strategy (mixed strategy, resp.)

In every finite extensive form game with perfect memory, for every mixed strategy (behavior strategy, resp.) there exists an outcome equivalent behavior strategy (mixed strategy, resp.)

Examples with imperfect memory where the proposition does not apply:

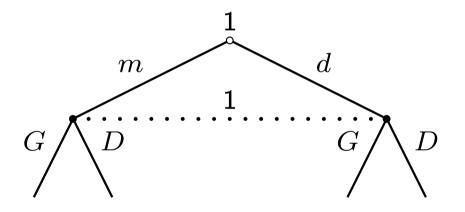
In every finite extensive form game with perfect memory, for every mixed strategy (behavior strategy, resp.) there exists an outcome equivalent behavior strategy (mixed strategy, resp.)

Examples with imperfect memory where the proposition does not apply:



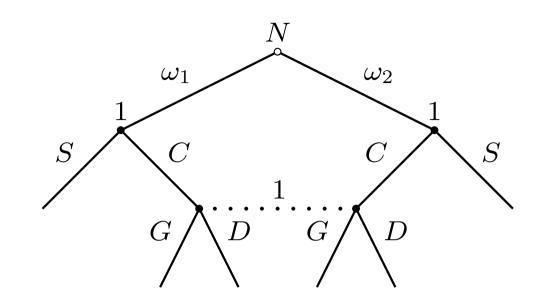
In every finite extensive form game with perfect memory, for every mixed strategy (behavior strategy, resp.) there exists an outcome equivalent behavior strategy (mixed strategy, resp.)

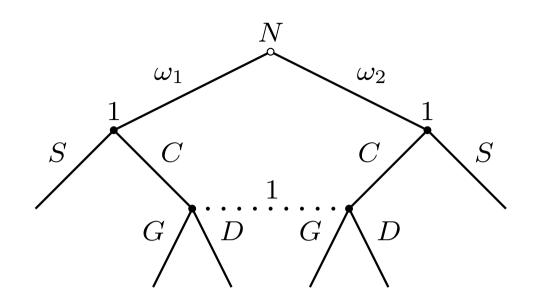
Examples with imperfect memory where the proposition does not apply:



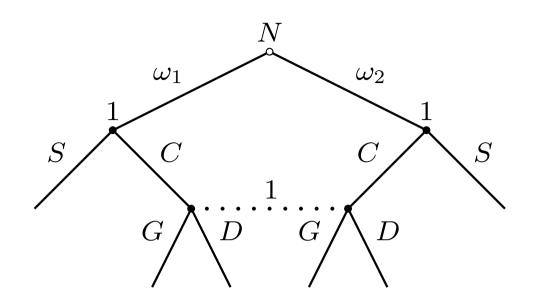
➡ The mixed strategy $\sigma_1(m,G) = \sigma_1(d,D) = 1/2$ has no equivalent behavior strategy

Game Theory





→ The mixed strategy $\sigma_1(C, C, G) = \sigma_1(C, C, D) = 1/2$ has an equivalent behavior strategy $(C \mid \omega_1, C \mid \omega_2, \frac{1}{2}G + \frac{1}{2}D \mid C)$



→ The mixed strategy $\sigma_1(C, C, G) = \sigma_1(C, C, D) = 1/2$ has an equivalent behavior strategy $(C \mid \omega_1, C \mid \omega_2, \frac{1}{2}G + \frac{1}{2}D \mid C)$

→ But the mixed strategy $\sigma_1(C, C, G) = \sigma_1(C, S, D) = 1/2$ has no equivalent behavior strategy





Some Nash equilibria are not "adequate" if players are fully rational because they rely on irrational behavior (incredible threats) off the equilibrium path

Some Nash equilibria are not "adequate" if players are fully rational because they rely on irrational behavior (incredible threats) off the equilibrium path

Examples: image image

Some Nash equilibria are not "adequate" if players are fully rational because they rely on irrational behavior (incredible threats) off the equilibrium path

Examples: image image

• Entry game: (No entry, price war)

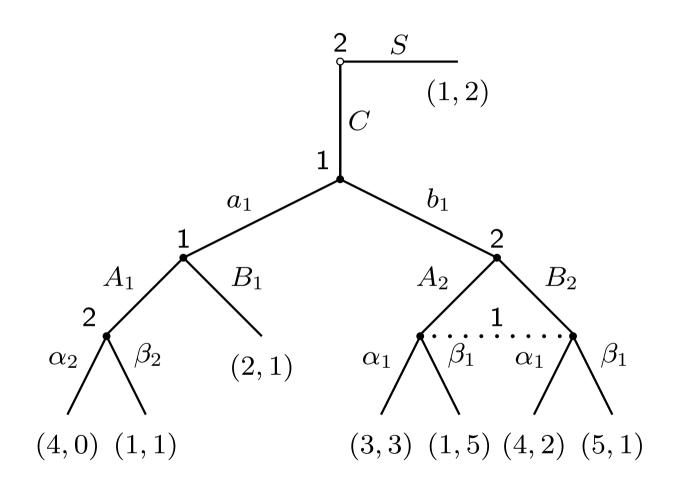
Some Nash equilibria are not "adequate" if players are fully rational because they rely on irrational behavior (incredible threats) off the equilibrium path

Examples: image image

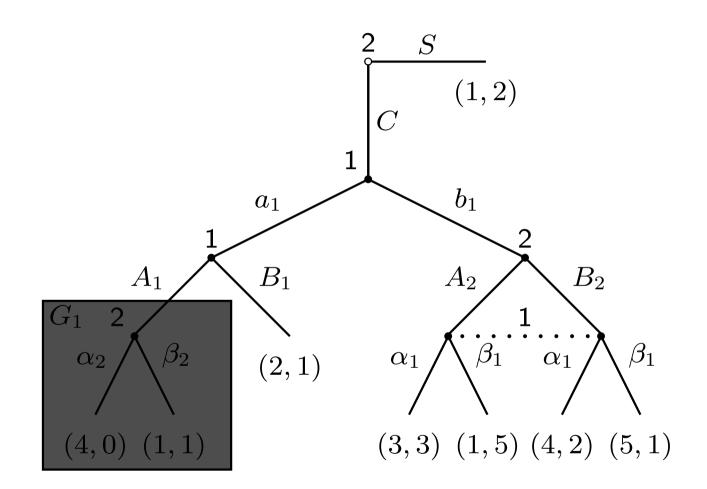
- Entry game: (No entry, price war)
- Ultimatum game: $((0,2), R\mathbf{R}A)$



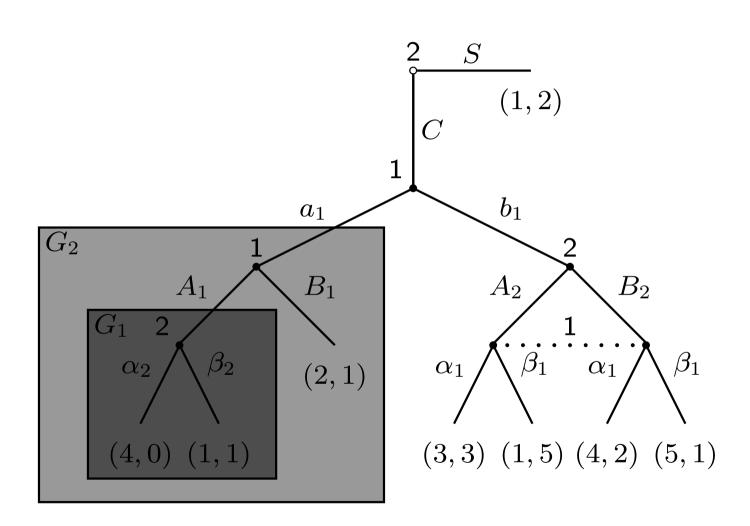




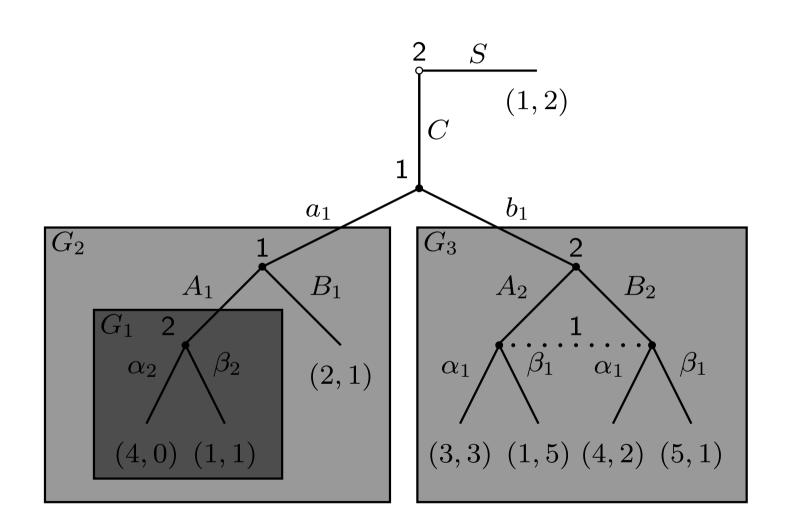




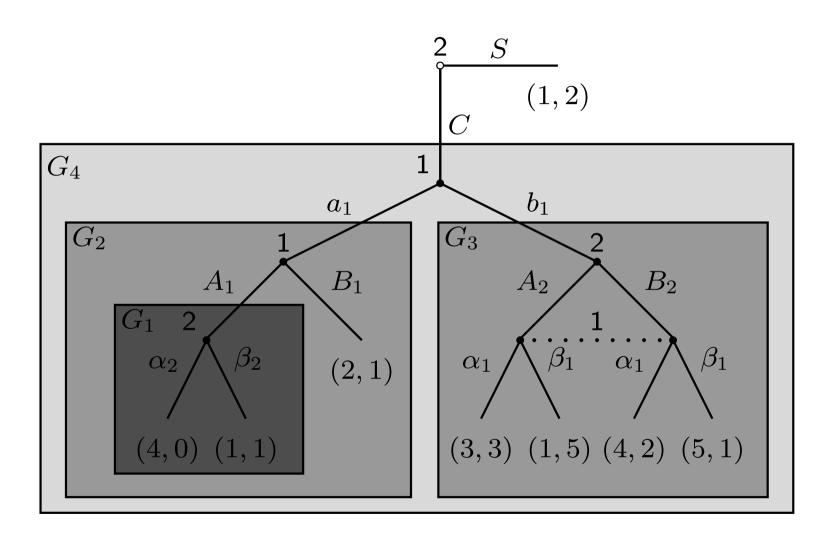




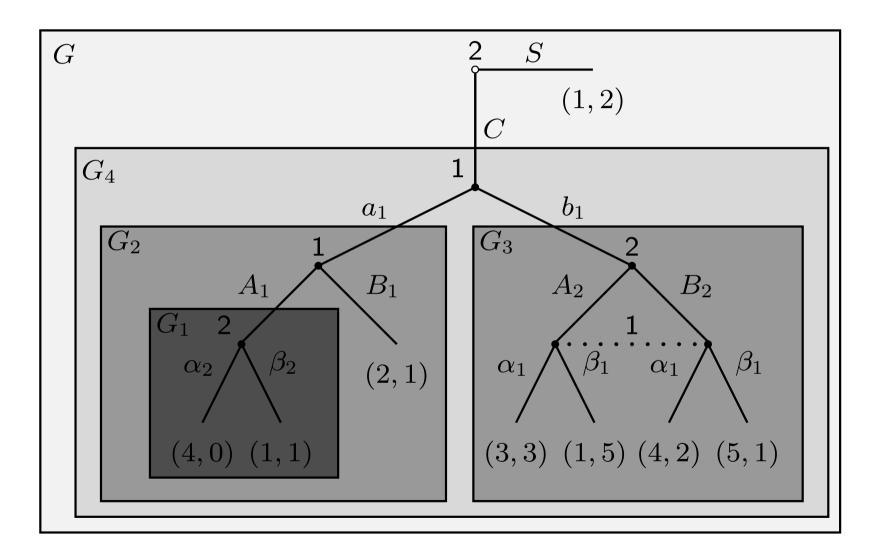














Subgames in previous examples?

Game Theory Subgames in previous examples?

Definition. (Selten, 1965)

A subgame perfect Nash equilibrium (SPNE) is a profile of strategies such that in each subgame the induced strategy profile is a Nash equilibrium of that subgame



Figure 2: Reinhard Selten (1930-)

Game Theory

 ${\ensuremath{\, \ensuremath{\, \ensuremath{\,$

 ${\ensuremath{\,\cong}}$ If there is no proper subgame then NE \Leftrightarrow SPNE

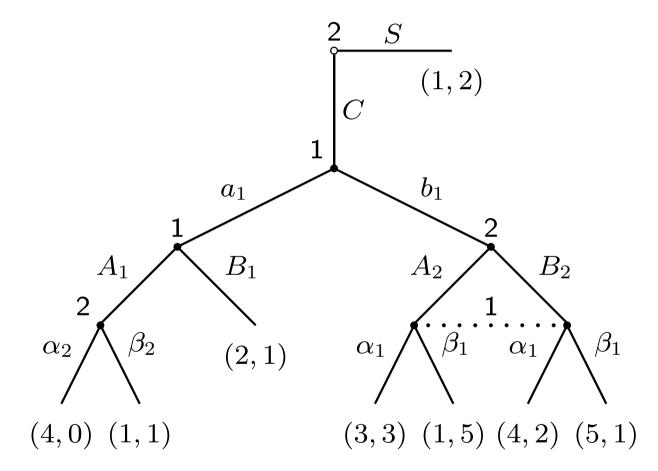
 ${\ensuremath{\,\cong\,}}$ If there is no proper subgame then NE \Leftrightarrow SPNE

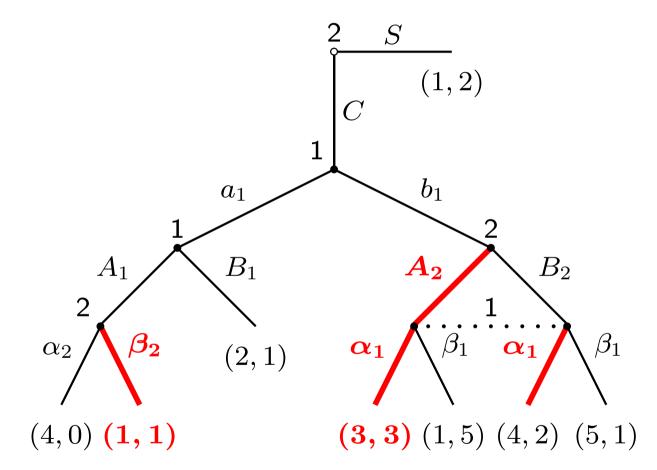
Proposition.

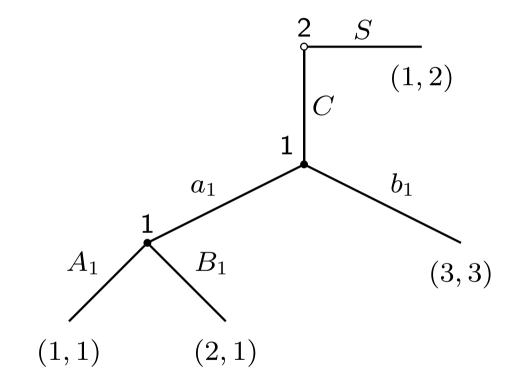
Every finite extensive form game has at least one subgame perfect equilibrium

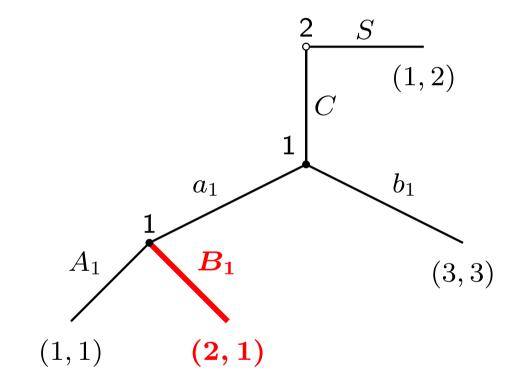


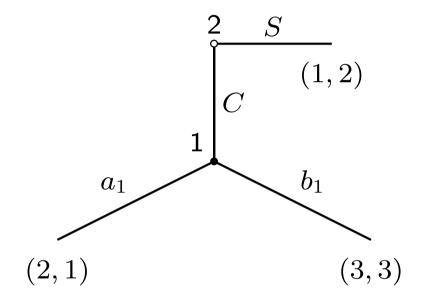


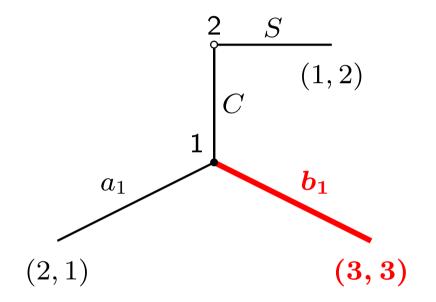




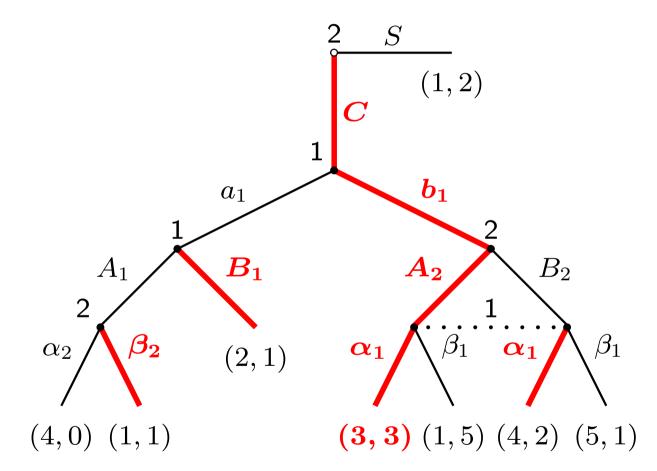








$$\begin{array}{c}
2 & S \\
\hline C \\
3,3)
\end{array}$$
(1,2)



Entry game.

Entry game. Only one SPNE : (Entry, Share)

Entry game. Only one SPNE : (Entry, Share)

Ultimatum game.

Ultimatum game. Two SPNE in pure strategies:

((2,0), AAA) and ((1,1), RAA)

Ultimatum game. Two SPNE in pure strategies:

((2,0),AAA) and ((1,1),RAA)

and a continuum in mixed strategies

 $((2,0), \sigma_2(AAA) \ge 1/2 \text{ and } ((1,1), \sigma_2(AAA) \le 1/2)$

with $\sigma_2(AAA) + \sigma_2(RAA) = 1$

Ultimatum game. Two SPNE in pure strategies:

((2,0),AAA) and ((1,1),RAA)

and a continuum in mixed strategies

 $((2,0), \sigma_2(AAA) \ge 1/2 \text{ and } ((1,1), \sigma_2(AAA) \le 1/2)$

with $\sigma_2(AAA) + \sigma_2(RAA) = 1$

Proposition. (Kuhn, 1953)

Every perfect information game has at least one subgame perfect equilibrium in pure strategies

Ultimatum game. Two SPNE in pure strategies:

((2,0),AAA) and ((1,1),RAA)

and a continuum in mixed strategies

 $((2,0), \sigma_2(AAA) \ge 1/2 \text{ and } ((1,1), \sigma_2(AAA) \le 1/2)$

with $\sigma_2(AAA) + \sigma_2(RAA) = 1$

Proposition. (Kuhn, 1953)

Every perfect information game has at least one subgame perfect equilibrium in pure strategies

Remarks.

Ultimatum game. Two SPNE in pure strategies:

((2,0), AAA) and ((1,1), RAA)

and a continuum in mixed strategies

 $((2,0), \sigma_2(AAA) \ge 1/2 \text{ and } ((1,1), \sigma_2(AAA) \le 1/2)$

with $\sigma_2(AAA) + \sigma_2(RAA) = 1$

Proposition. (Kuhn, 1953)

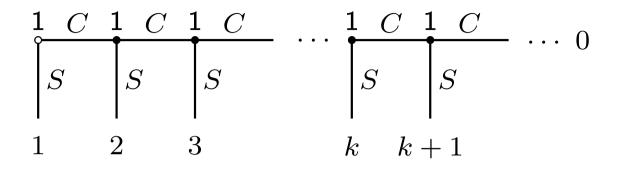
Every perfect information game has at least one subgame perfect equilibrium in pure strategies

Remarks.

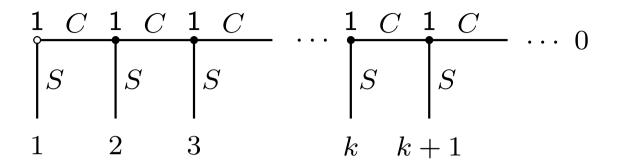
The set of actions at every information must be finite: A = [0, 1) and $u_i(a) = a$ implies no SPNE

The length of the game must be finite:

The length of the game must be finite:



The length of the game must be finite:



⇐ Example to analyze: "winning without knowing how" pdf

Game Theory Example. Incredible threat / commitment

Example. Incredible threat / commitment

Army 1 of country 1 wants to attack army 2 of country 2 which is on an island between the two countries. If army 1 attacks then army 2 can choose between fighting and retreating using the bridge between the island and country 2. Each army prefers getting the island instead of letting it to its opponent, but the worst outcome is war

Example. Incredible threat / commitment

Army 1 of country 1 wants to attack army 2 of country 2 which is on an island between the two countries. If army 1 attacks then army 2 can choose between fighting and retreating using the bridge between the island and country 2. Each army prefers getting the island instead of letting it to its opponent, but the worst outcome is war

Example. Incredible threat / commitment

Army 1 of country 1 wants to attack army 2 of country 2 which is on an island between the two countries. If army 1 attacks then army 2 can choose between fighting and retreating using the bridge between the island and country 2. Each army prefers getting the island instead of letting it to its opponent, but the worst outcome is war

 \Rightarrow Show that army 2 can increase its payoff by destroying the bridge in advance (assuming that this action is observed by army 1)

Example. Incredible threat / commitment

Army 1 of country 1 wants to attack army 2 of country 2 which is on an island between the two countries. If army 1 attacks then army 2 can choose between fighting and retreating using the bridge between the island and country 2. Each army prefers getting the island instead of letting it to its opponent, but the worst outcome is war

 \Rightarrow Show that army 2 can increase its payoff by destroying the bridge in advance (assuming that this action is observed by army 1)

Consider the initial situation again

Example. Incredible threat / commitment

Army 1 of country 1 wants to attack army 2 of country 2 which is on an island between the two countries. If army 1 attacks then army 2 can choose between fighting and retreating using the bridge between the island and country 2. Each army prefers getting the island instead of letting it to its opponent, but the worst outcome is war

 \Rightarrow Show that army 2 can increase its payoff by destroying the bridge in advance (assuming that this action is observed by army 1)

Consider the initial situation again

A If decisions are simultaneous, what kind of game is it? (if the island turns out to be non-occupied, consider intermediate payoffs between being alone on the island and letting it to the enemy)







Firm i = 1, 2 produces q_i with zero fixed cost and constant marginal cost $\lambda > 0$



Firm i = 1, 2 produces q_i with zero fixed cost and constant marginal cost $\lambda > 0$ Linear inverse demand: $p(q_1 + q_2) = a - (q_1 + q_2)$, where $a > \lambda$

Firm i = 1, 2 produces q_i with zero fixed cost and constant marginal cost $\lambda > 0$ Linear inverse demand: $p(q_1 + q_2) = a - (q_1 + q_2)$, where $a > \lambda$ Profit of firm i:

$$u_i(q_1, q_2) = p(q_1 + q_2) q_i - \lambda q_i = q_i(a - \lambda - (q_1 + q_2))$$

Firm i = 1, 2 produces q_i with zero fixed cost and constant marginal cost $\lambda > 0$ Linear inverse demand: $p(q_1 + q_2) = a - (q_1 + q_2)$, where $a > \lambda$ Profit of firm i:

$$u_i(q_1, q_2) = p(q_1 + q_2) q_i - \lambda q_i = q_i(a - \lambda - (q_1 + q_2))$$

Sequential decisions: Firm 1 (the *leader*) chooses (irreversibly) q_1 and then firm 2 (the *follower*) chooses q_2 knowing q_1

Firm i = 1, 2 produces q_i with zero fixed cost and constant marginal cost $\lambda > 0$ Linear inverse demand: $p(q_1 + q_2) = a - (q_1 + q_2)$, where $a > \lambda$ Profit of firm i:

$$u_i(q_1, q_2) = p(q_1 + q_2) q_i - \lambda q_i = q_i(a - \lambda - (q_1 + q_2))$$

Sequential decisions: Firm 1 (the *leader*) chooses (irreversibly) q_1 and then firm 2 (the *follower*) chooses q_2 knowing q_1

Firm 1's strategy: quantity q_1 (as in the Cournot model)

Firm i = 1, 2 produces q_i with zero fixed cost and constant marginal cost $\lambda > 0$ Linear inverse demand: $p(q_1 + q_2) = a - (q_1 + q_2)$, where $a > \lambda$ Profit of firm i:

$$u_i(q_1, q_2) = p(q_1 + q_2) q_i - \lambda q_i = q_i(a - \lambda - (q_1 + q_2))$$

Sequential decisions: Firm 1 (the *leader*) chooses (irreversibly) q_1 and then firm 2 (the *follower*) chooses q_2 knowing q_1

Firm 1's strategy: quantity q_1 (as in the Cournot model) Firm 2's strategy: function $q_2^*(q_1)$

$$q_2^*(q_1) = BR_2(q_1) = \arg\max_{q_2} u_1(q_1, q_2) = \frac{a - \lambda - q_1}{2}$$

$$q_2^*(q_1) = BR_2(q_1) = \arg\max_{q_2} u_1(q_1, q_2) = \frac{a - \lambda - q_1}{2}$$

Optimal production of firm 1 given firm 2's response maximize

$$u_1(q_1, q_2^*(q_1)) = q_1(a - \lambda - (q_1 + q_2^*(q_1))) = \frac{1}{2}q_1(a - \lambda - q_1)$$

$$q_2^*(q_1) = BR_2(q_1) = \arg\max_{q_2} u_1(q_1, q_2) = \frac{a - \lambda - q_1}{2}$$

Optimal production of firm 1 given firm 2's response maximize

$$u_1(q_1, q_2^*(q_1)) = q_1(a - \lambda - (q_1 + q_2^*(q_1))) = \frac{1}{2}q_1(a - \lambda - q_1)$$

i.e., $q_1^* = \frac{a-\lambda}{2} \Rightarrow q_2^*(q_1^*) = \frac{a-\lambda}{4}$

Extensive Form Games

Game Theory Backward induction solution.

$$q_2^*(q_1) = BR_2(q_1) = \arg\max_{q_2} u_1(q_1, q_2) = \frac{a - \lambda - q_1}{2}$$

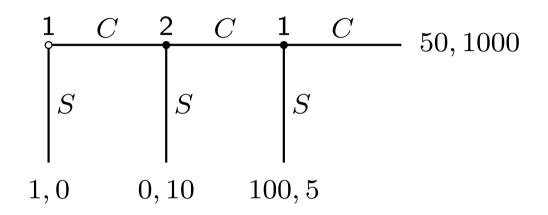
Optimal production of firm 1 given firm 2's response maximize

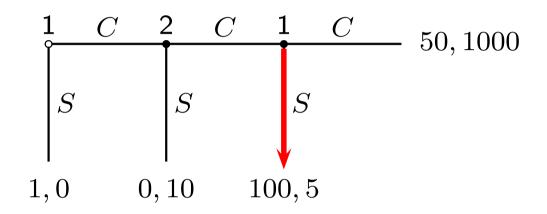
$$u_1(q_1, q_2^*(q_1)) = q_1(a - \lambda - (q_1 + q_2^*(q_1))) = \frac{1}{2}q_1(a - \lambda - q_1)$$

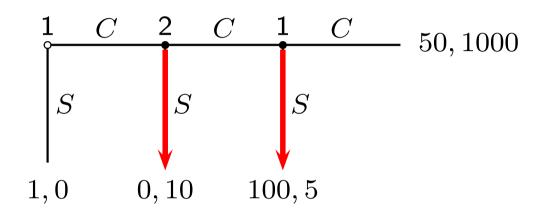
i.e.,
$$q_1^* = rac{a-\lambda}{2} \Rightarrow q_2^*(q_1^*) = rac{a-\lambda}{4}$$

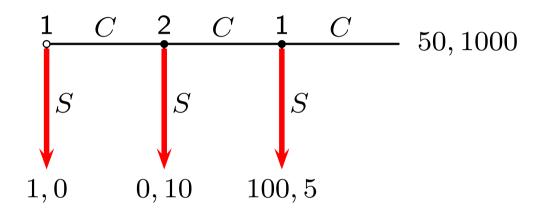
	Cournot		Stackelberg (firm 1 leader)	
Firm 1	$q_1 = \frac{a-\lambda}{3}$	$u_1 = \frac{(a-\lambda)^2}{9}$	$q_1 = \frac{a-\lambda}{2}$	$u_1 = \frac{(a-\lambda)^2}{8}$
Firm 2	$q_2 = \frac{a-\lambda}{3}$	$u_2 = \frac{(a-\lambda)^2}{9}$	$q_2 = \frac{a-\lambda}{4}$	$u_2 = rac{(a-\lambda)^2}{16}$

Table 1: Productions and profits in the linear Cournot and Stackelberg duopolies

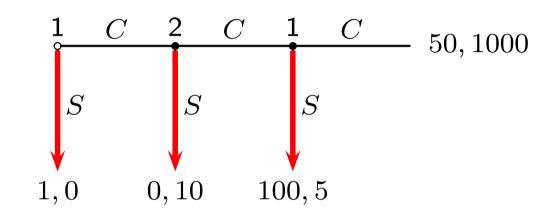








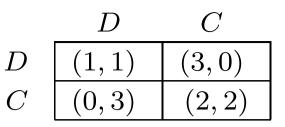
Backward Induction "Paradox"



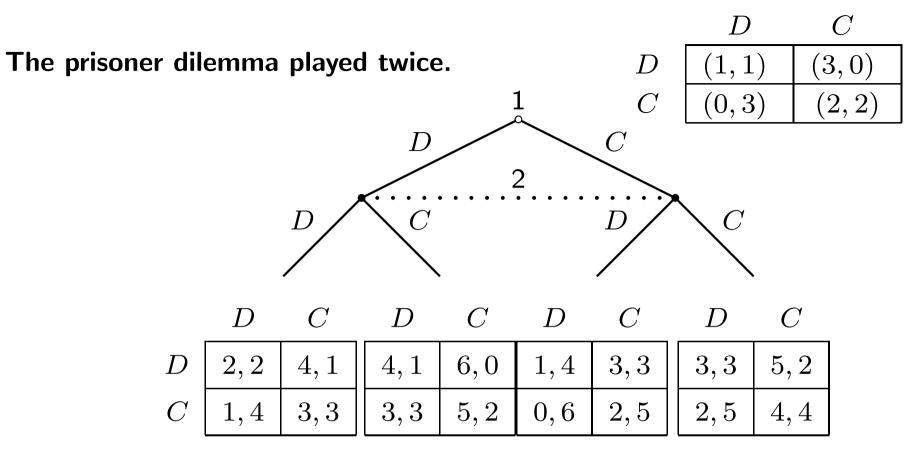
What should player 2 do/think if he actually has to play?

Extensive Form Games

The prisoner dilemma played twice.

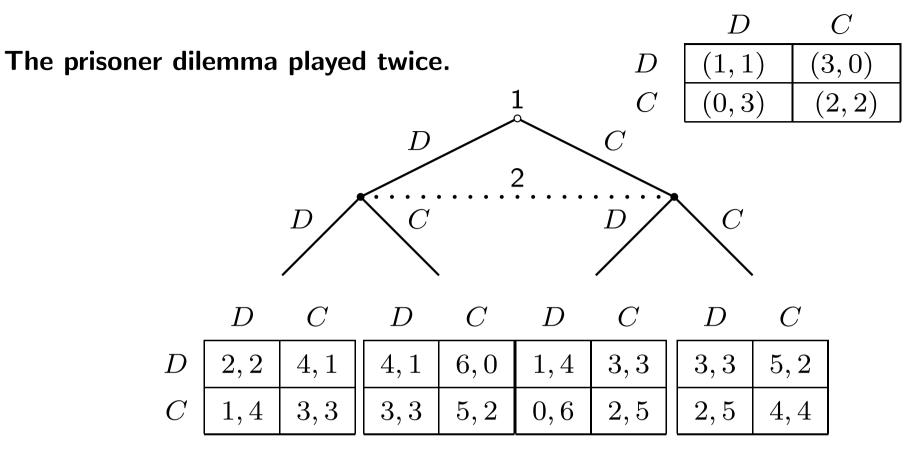


Extensive Form Games



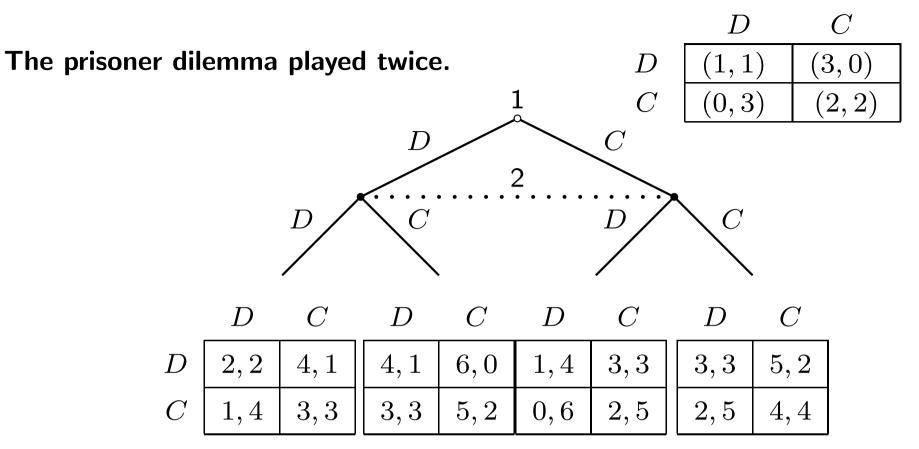


Extensive Form Games



Unique NE (SPNE): both players defect in both periods

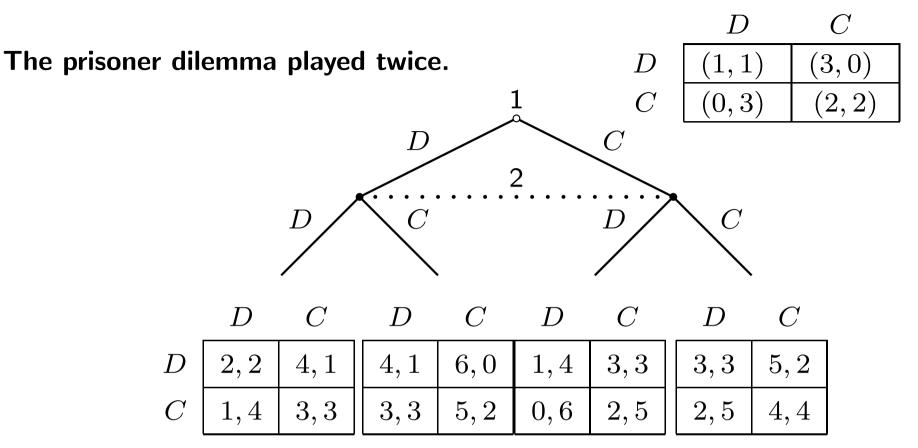




Unique NE (SPNE): both players defect in both periods

Same result whatever the length (finite and commonly known) of the game

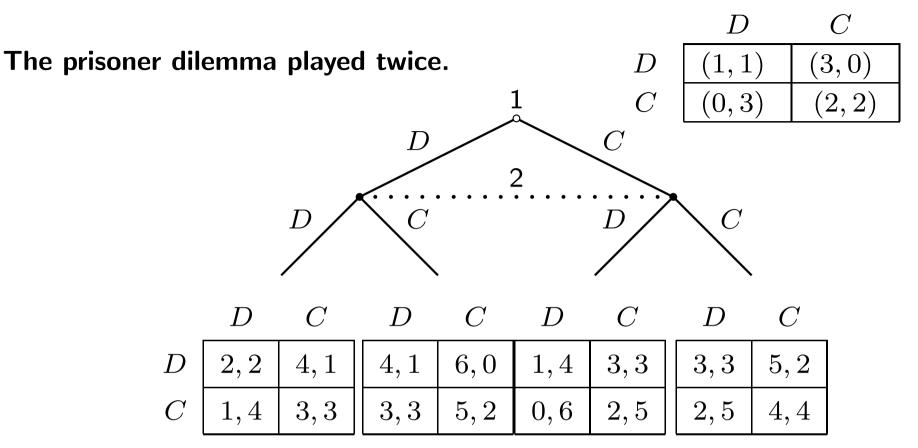




Unique NE (SPNE): both players defect in both periods

Same result whatever the length (finite and commonly known) of the game What should a player do (think) if his partner cooperate?





Unique NE (SPNE): both players defect in both periods

Same result whatever the length (finite and commonly known) of the game What should a player do (think) if his partner cooperate?

Remark. We will see that infinite repetition allows cooperation

Game Theory References

HARSANYI, J. C. (1967–1968): "Games with Incomplete Information Played by Bayesian Players. Parts I, II, III," Management Science, 14, 159–182, 320–334, 486–502.

- KUHN, H. W. (1953): "Extensive Games and the Problem of Information," in Contributions to the Theory of Games, ed. by H. W. Kuhn and A. W. Tucker, Princeton: Princeton University Press, vol. 2.
- SELTEN, R. (1965): "Spieltheoretische Behandlung eines Oligopolmodells mit Nachfrageträgheit," Zeitschrift für dis gesamte Staatswissenschaft, 121, 301–324 and 667–689.